

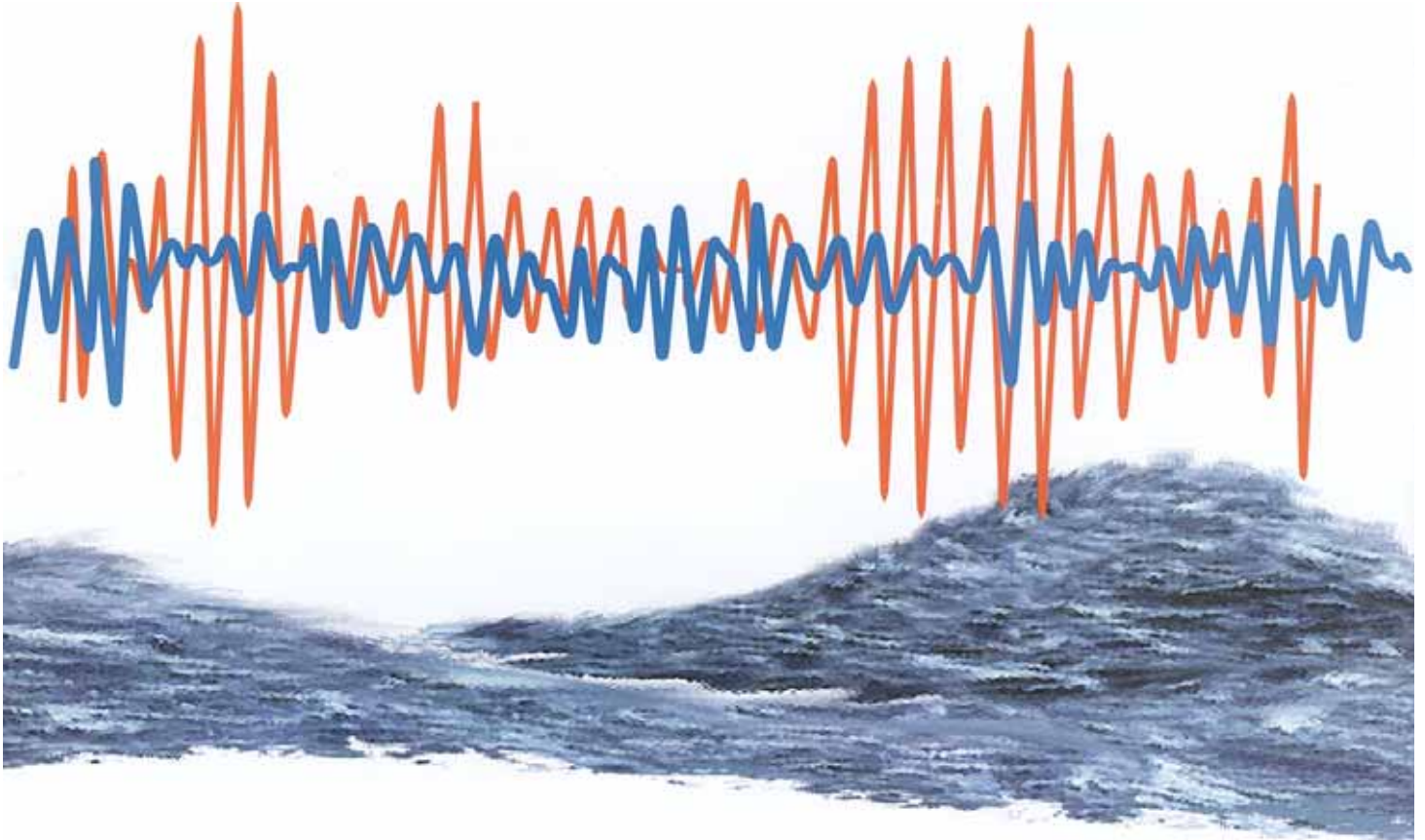


Rolls-Royce

Intering Products

Intering Tank Stabilizers

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Improve Comfort &
Operating Performance

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INTERING Stabilizers



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**on Offshore, Research
and Service Vessels and on
Navy and Government Ships**

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1. Brief System and Feature Description

Brief System and Feature Description

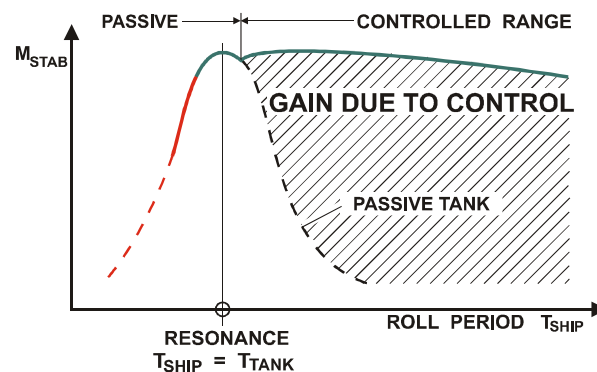
The passive controlled INTERING Stabiliser is based on a U-shaped tank system half filled with water. Side tanks are connected by a water cross duct and air cross duct(s) are installed for air exchange between side tanks. Stabiliser valves are integrated into the air cross duct.

The system is called passive since the attacking sea, which caused the roll of the vessel, supplied the necessary energy for roll reduction. The roll of the vessel is used to cause an oscillatory athwartships movement of the tank water.

The controlled part of the system is the 'active' influence of system control together with the stabiliser valves by cyclic blocking of tank water on the upwards moving ship side to adapt the tank period to the actual ship's roll period.

The dimensions of the tank are so defined that the resulting natural tank period corresponds about the expected shortest ships roll period. Vessel's roll period is changing dependent on loading and sea condition.

Due to the 'active' tank period tuning the system is able to ensure the right phase lag between tank water oscillation and ship's roll motion to maintain the stabilising effect over a wide range of ship's roll periods. The effect is shown in following diagram.



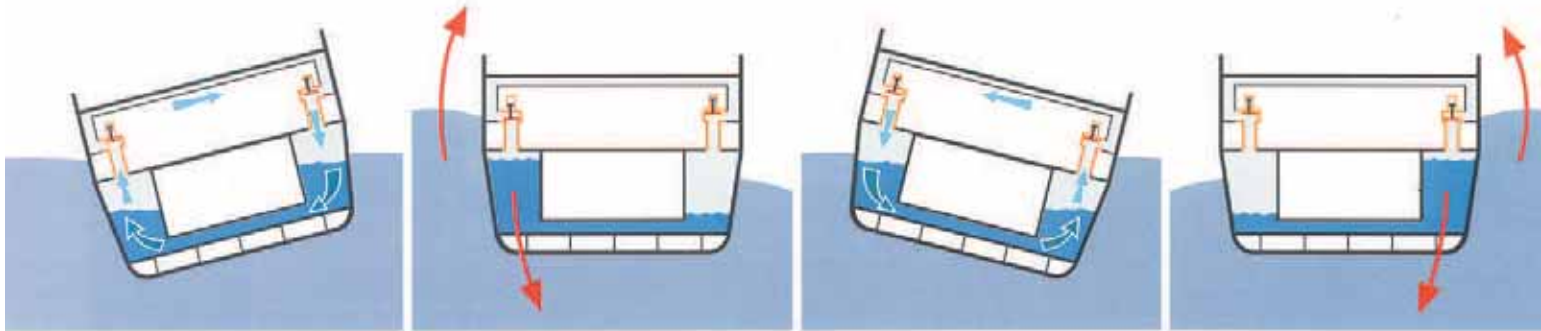
System Features:

- space between u-shape tank system can be used for other purposes
- system works fully automatic
- system efficiency is independent from ship speed even at zero speed
- tank water filling is constant for all loading conditions
- Security Principle: closing of stabiliser valves to prevent uncontrolled water flow in case of black out or loss of electric power or control air
- system maintenance is reduced to a minimum
- system works reliable and is proven since more than 30 years
- 3 years guarantee is standard

For more detailed function description and references pls. see following pages.

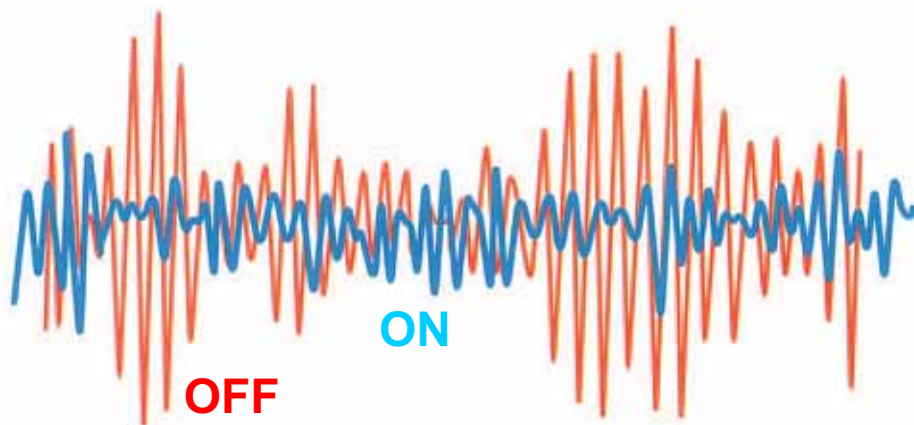
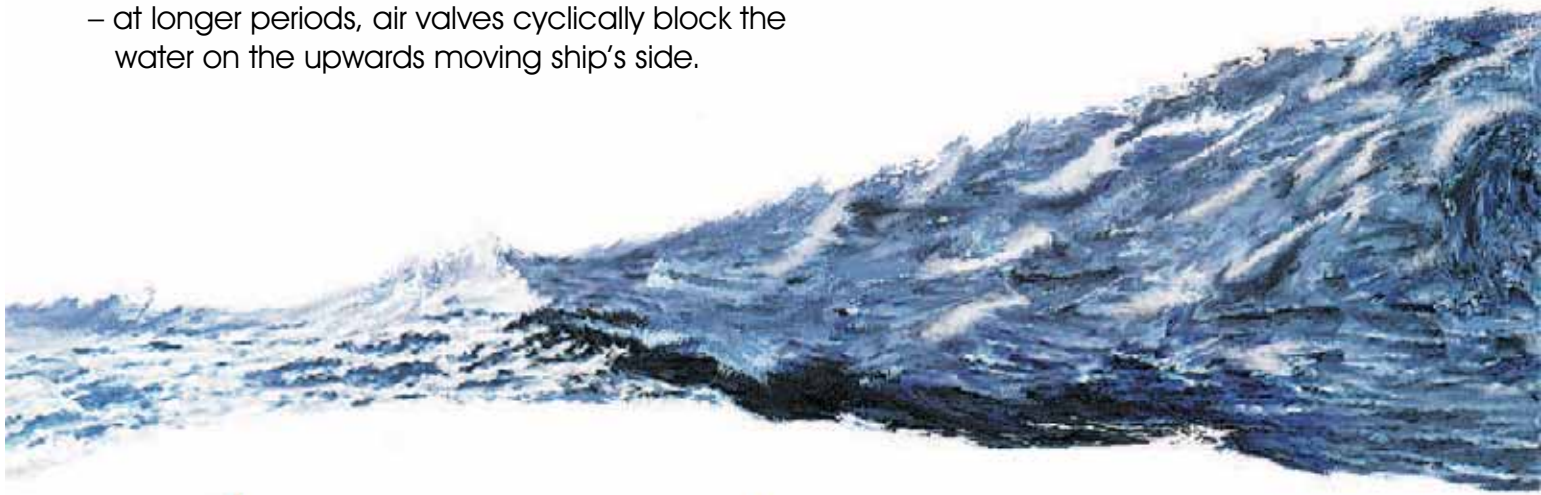


Roll reduction with Energy supplied by the sea



Caused by the ship's roll, the tank water oscillates athwartship to counteract the roll:

- at short periods by natural oscillation,
- at longer periods, air valves cyclically block the water on the upwards moving ship's side.



Automatic control reacts within 1/4 roll period
Roll reduction in normal irregular seas approximately 40 - 60 %



No moving parts in water

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2. General Information and Phase Cycle Diagrams

General Information and Phase Cycle Diagrams

1 TANK ARRANGEMENT

U-shaped tank system, athwartships arranged, half-filled with water, designed to reduce the vessel's roll motion at sea, independently from the ship's speed.

2 MAIN COMPONENTS:

- Control Unit
- Stabilizer Valves
- Pneumatic Control Devices
- Remote Control Panel

3 STABILIZER OPERATION AT SEA

The effect of the INTERING Stabilizer is based on an advantageous physical principle:

The roll of the vessel is used to cause an oscillatory athwartships movement of water in an U-shaped tank system. Due to the design of the tanks and by the automatic control blocking the water cyclically on the upwards moving ship's side, the movement of the tank water is permanently tuned to counteract and reduce the roll.

Thus the sea, in causing the vessel's roll, delivers the necessary energy to reduce the roll.

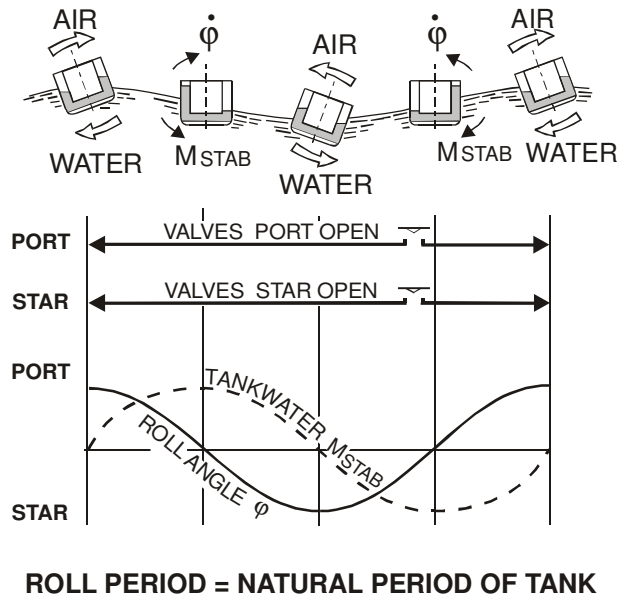
Two main operational ranges are to be distinguished: a purely passive operation at short periods and the passive controlled range at periods longer than the natural period of the tank system.

4 THE PASSIVE OPERATIONAL RANGE

The dimensions of the INTERING Stabilizer are so defined that the natural period of the tank (time for a full oscillation of the tank fluid) has about the same value as the shortest roll period to be expected in the service of the vessel. When the ship rolls with this period the stabilizer valves (see Fig. A) are kept continuously open and the tank fluid oscillates athwartships within the U-shaped tank system in such a way that it always obtains its maximum level in the side tank which is moving upwards.

This state is called resonance and is demonstrated as a phase cycle in Fig. A at the next page.

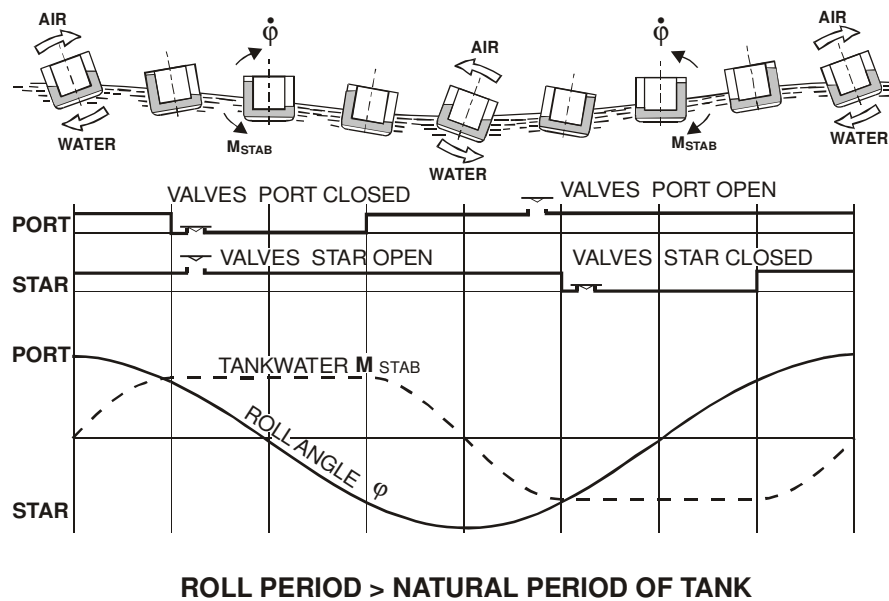
4.1 Fig. A: Phase Cycle - Ship and Tank in Resonance



5 THE EFFECT OF THE INTERING CONTROL

As soon as the ship rolls with periods slightly longer than the natural period of the tank system due to reduced GM values or the effect of the waves, the tank fluid is immediately adapted to the changed roll motion by the automatic control. This is shown schematically in Fig. B.

5.1 Fig. B: Phase Cycle for Roll Periods longer than natural Period of Tank



INTERING Stabilizers



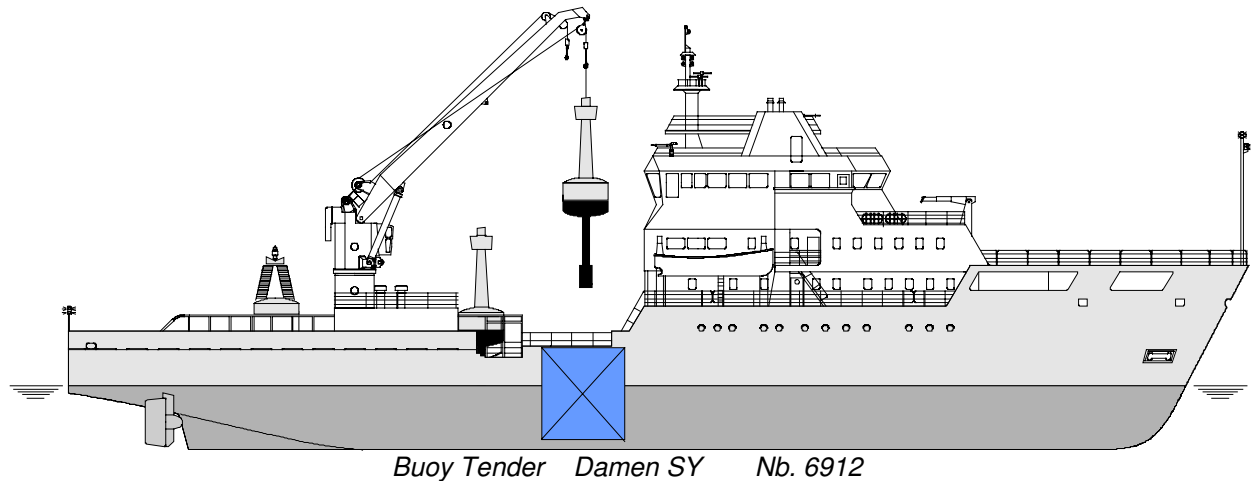
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3. Stabilizer Function Schemes

- Buoy Tender / DAMEN SY NB. 6912
- Aids to Navigation Vessel / Ferguson SB NB. 706

INTERING SYSTEM on Buoy Tender for Northern Lighthouse and Commissioners of Irish Lights



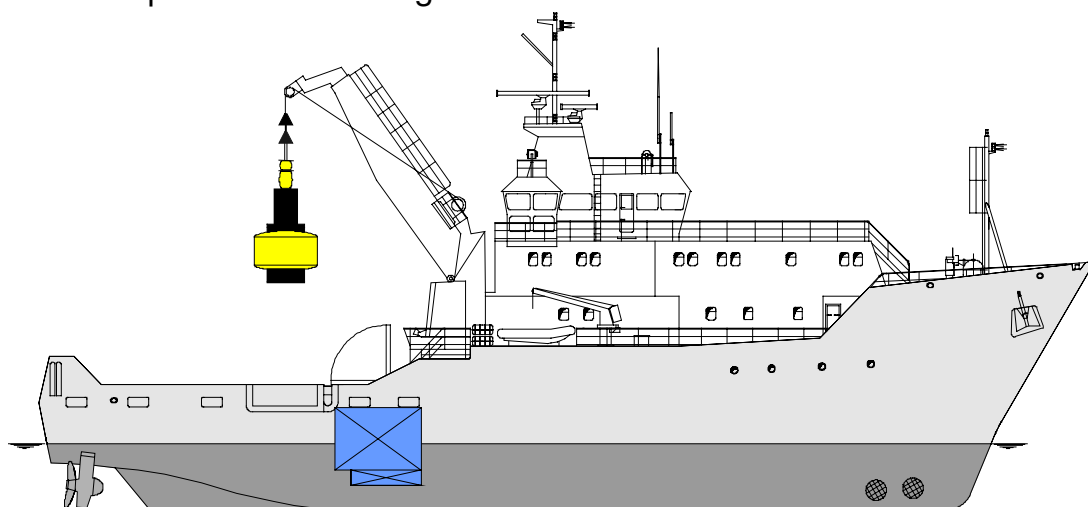
INTERING Stabilizer

- U-shaped stabilizer tank installed in the side tanks.
- 50% roll reduction in average:
 - Extends operation performance
 - Increases crews comfort
 - Reduces ship's resistance

INTERING Heavy Fluid

OPERATING LIQUID FOR STABILIZER TANK

- Increases volume efficiency by 48%
- No tank heating required
- No special tank coating since it inhibits corrosion of steel



Aids to Navigation Tender Ferguson Shipbuilders Nb. No. 709

INTERING Stabilizers



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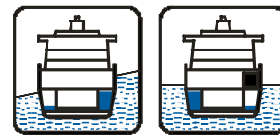
4. INTERING Stabilizer in Practical Operation

Extracts of Sea Trial Report MV "Melville"

- Presentation of roll recorder strips (Stabilizer: On/Off)
 - Overall Reduction of the System

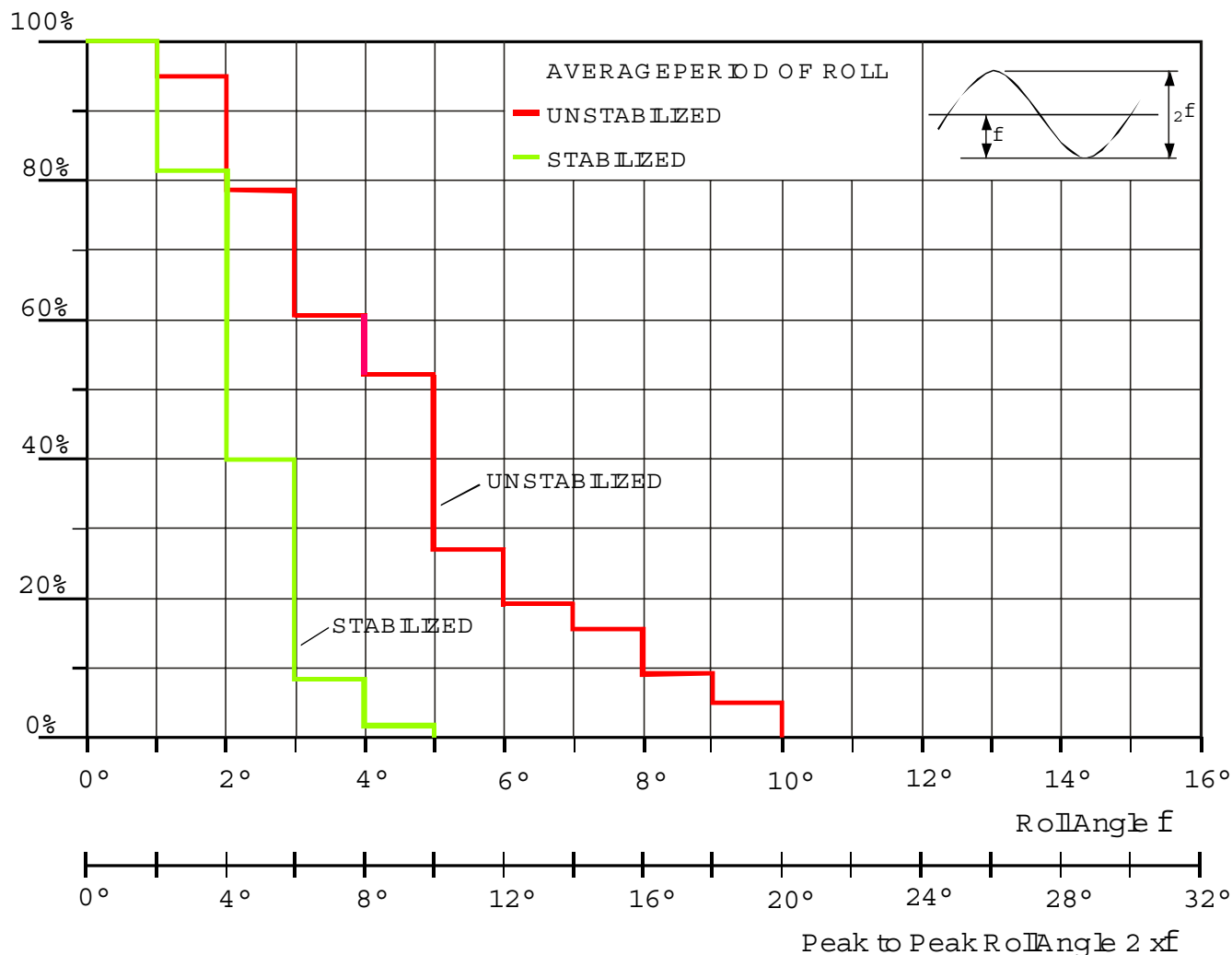
Sea Trial Report

Ship : MV MELVILLE"
 Newbuilding /No.: NQEA /200
 INTERING Ref.No.: 21092



INTERING
 14.04.2000

Fig. 1 : Relative Frequency Distribution - Trial1 + Trial2



Definition of overall reduction:

Area between stabilized and unstabilized curves
 divided by area below unstabilized curve.

Overall reduction for tests No.1 and No.2 :

$$\frac{(SR)_U - (SR)_S}{(SR)_U} \cdot 100 \% = \frac{459 - 232}{459} \cdot 100 \% = 49.5 \%$$

INTERING Stabilizers



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5. INTERING Stabilizer References for Offshore, Research and Service Vessels and Navy and Government Ships

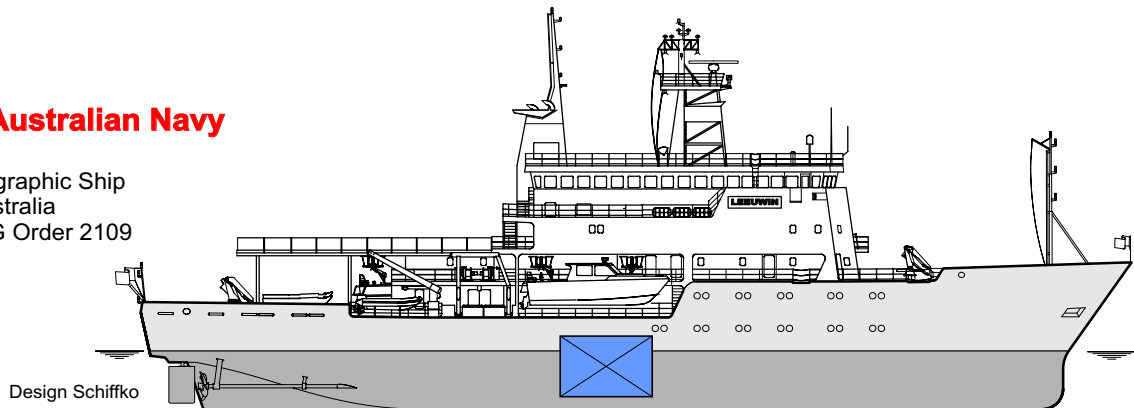
INTERING Stabilizer System on Research Vessels



Rolls-Royce

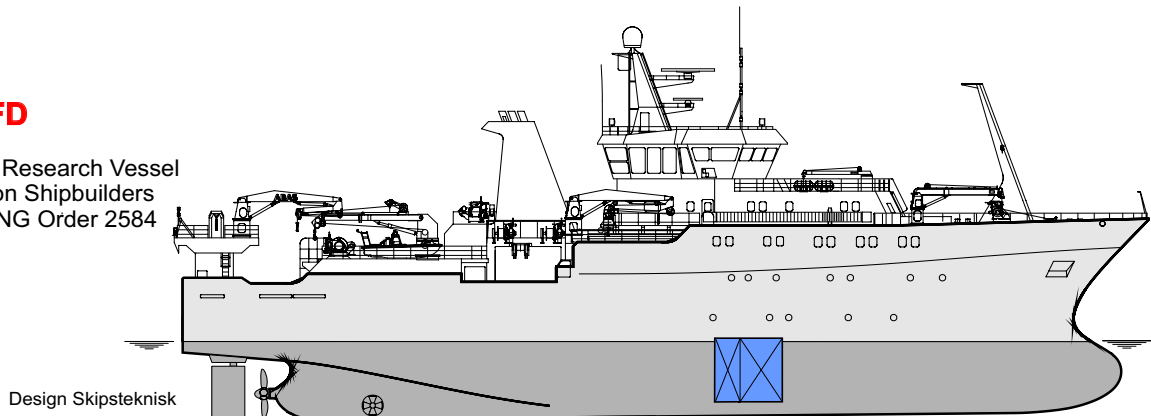
Royal Australian Navy

2 x Hydrographic Ship
NQE Australia
INTERING Order 2109



SOAFD

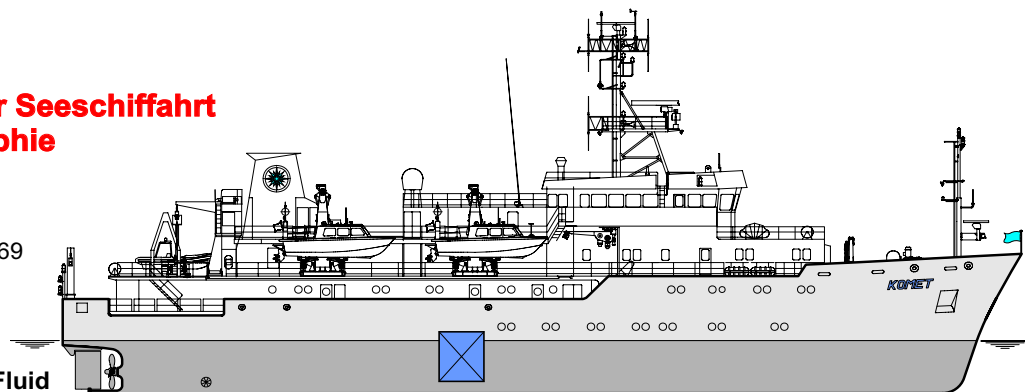
Fishery Research Vessel
Ferguson Shipbuilders
INTERING Order 2584



Bundesamt für Seeschifffahrt und Hydrographie

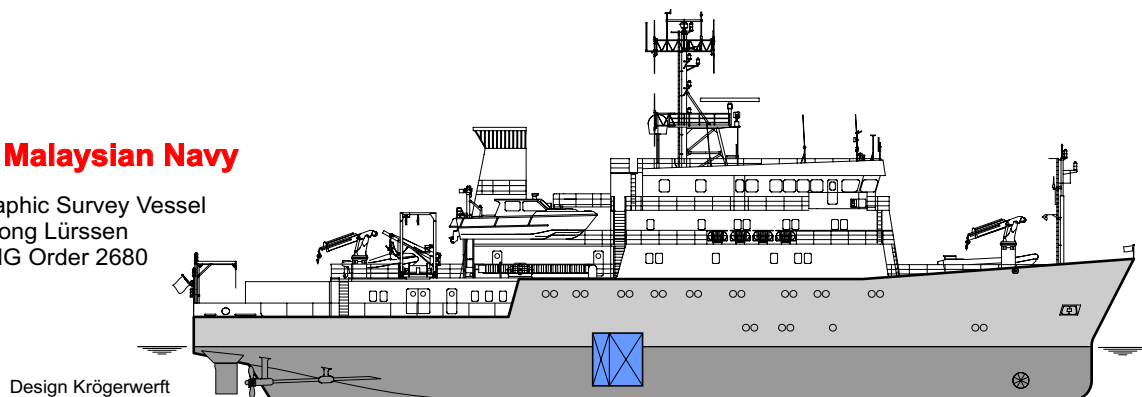
Survey Vessel
Krögerwerft
INTERING Order 2269

INTERING Heavy Fluid



Royal Malaysian Navy

Hydrographic Survey Vessel
Hong Leong Lürssen
INTERING Order 2680



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INTERING System on Offshore Vessels



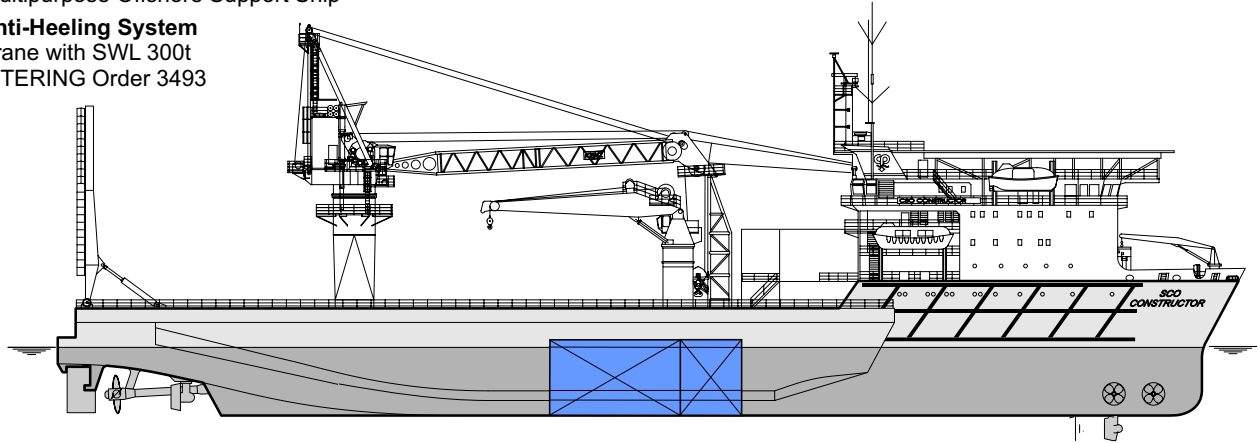
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Coflexip Stena Offshore

Multipurpose Offshore Support Ship

Anti-Heeling System

Crane with SWL 300t
INTERING Order 3493

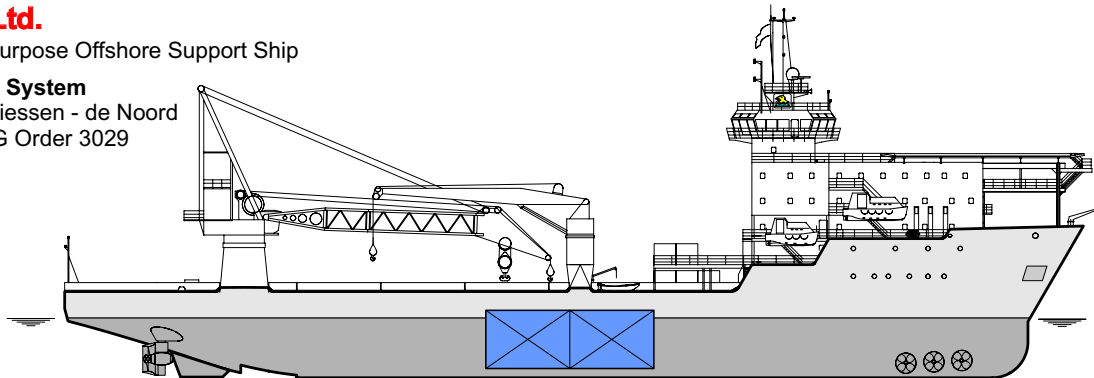


Toisa Ltd.

2 x Multipurpose Offshore Support Ship

Stabilizer System

van der Giessen - de Noord
INTERING Order 3029

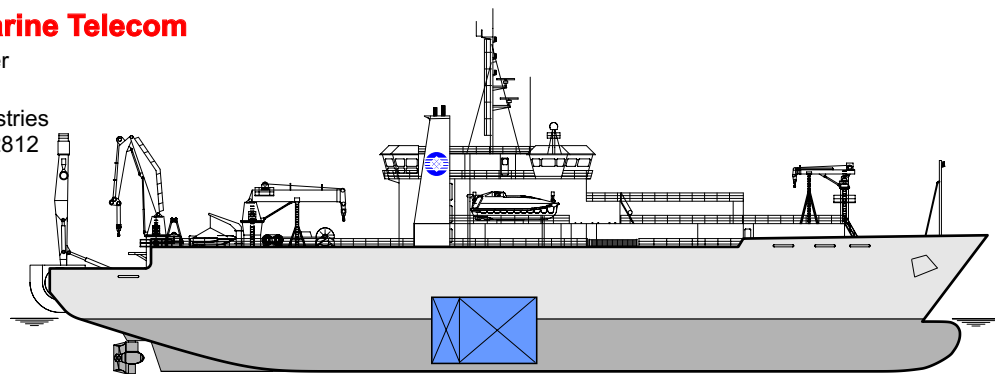


Korea Submarine Telecom

95,6 m Cable Layer

Stabilizer System

Hanjin Heavy Industries
INTERING Order 2812

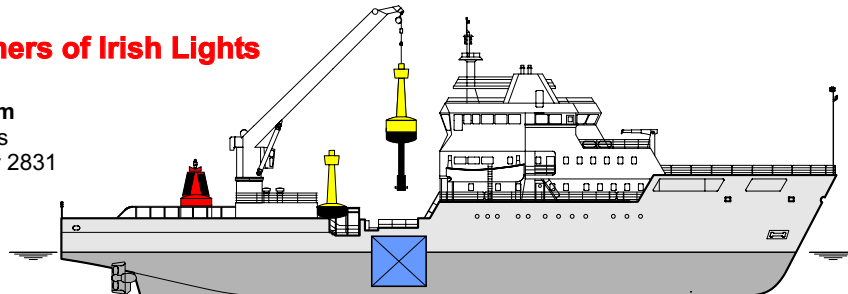


Commissioners of Irish Lights

Buoy Tender

Stabilizer System

Damen Shipyards
INTERING Order 2831



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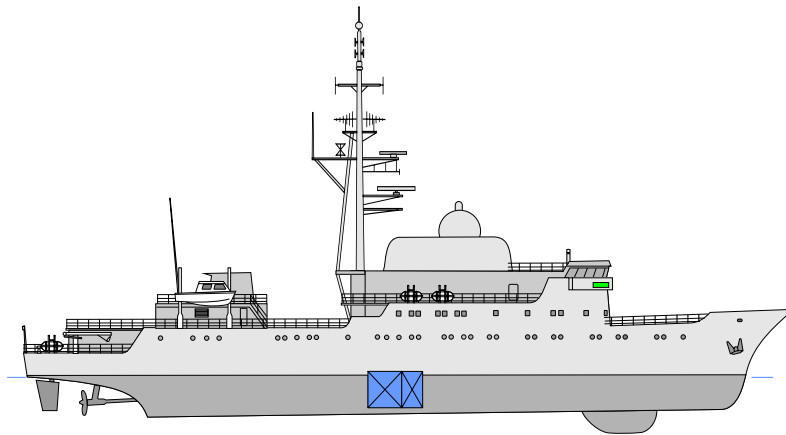
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INTERING Stabilizer System on Navy and Government Ships

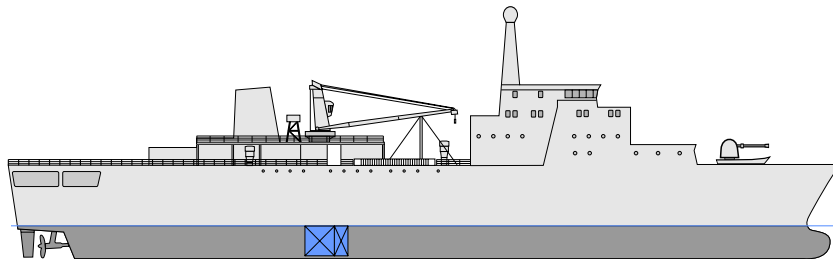


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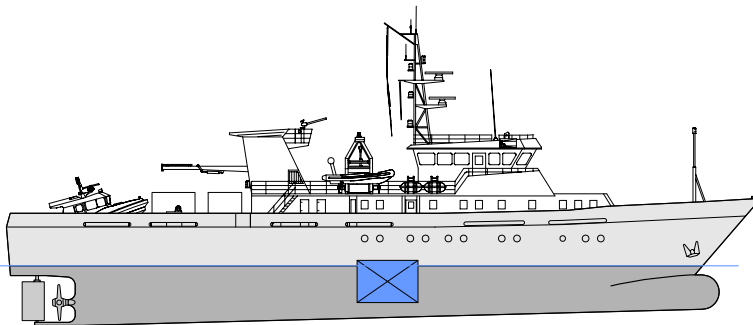
German Navy

Reconnaissance / Command Ship
LBP: 75,7m; B: 14,6m, Displ: 3300t
260tm Stabilizer Moment
130t Weight Tankfilling
Flensburger Schiffbau
INTERING Order 864



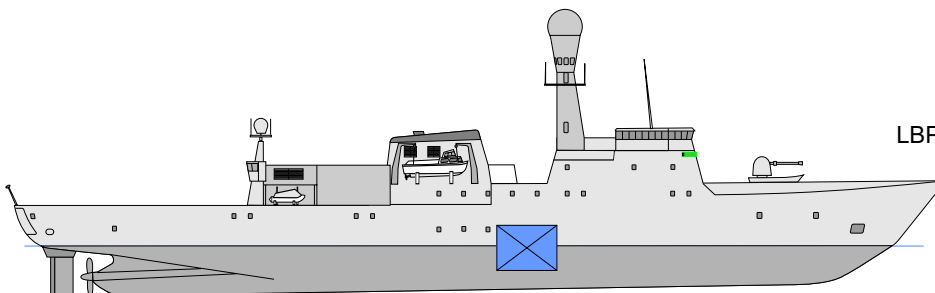
Malaysian Navy

MP Training / Support Ship
LBP: 90m; B: 15m; Displ: 4500t
420tm Stabilizer Moment
150t Weight Tankfilling
Korea Tacoma Marine
INTERING Order 853



Mauretanian State

Fishery Survey Ship
LBP: 54m; B: 10.6; Displ: 970t
60tm Stabilizer Moment
44t Weight Tankfilling
Fassmer Werft
INTERING Order 2990



Royal Danish Navy

Patrol Frigate
LBP: 99.75m; B: 14.4m; Displ: 5300t
INTERING STABILIZER
+ ICE- HEELING
330tm Stabilizer Moment
143t Weight Tankfilling
Svendborg Vaerft
INTERING Order 1317

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INTERING Stabilizer on "POLE STAR"
Northern Lighthouse Aids to Navigation Tender



Aids to Navigation Tender --- S1

Ferguson Shipbuilders Nb. No. 709

INTERING Stabilizer on "Merikarhu"
Finnish Board of Navigation --- Patrol Vessel



Patrol Vessel --- S1

Finnyards Nb. No. 406

**INTERING Stabilizer on “JAMES CLARK ROSS”
British Antarctic Survey --- Polar Research Vessel**



Research Vessel --- S2 EB3

Swan Hunter Shipbuilders Ltd. Nb. No. 132

**INTERING Stabilizer on “POLARSTERN”
German Government --- Polar Research Vessel**



Polar Research Vessel --- S2 EB3

HDW-Nobiskrug. Nb. No. 787

INTERING Stabilizer on “Seaway Condor”
Stolt – Nielsen Rederi AB --- Diving Support Vessel



Diving Support --- S1 K1

HDW – Nobiskrug Nb. No.: 710

INTERING Stabilizer on “TOISA PERSEUS”
Toisa --- Offshore Support Vessel



MP Offshore Support --- S2

van der Giessen – de Noord Nb. No.: 972

INTERING Stabilizer on "SVALBARD" Norwegian Coast Guard Vessel



Coast Guard Vessel --- S1 Langsten AS Nb. No. 108

INTERING Stabilizer on "ARGUIN" State of Mauretania



Fishery Surveillance Vessel --- S1

Fr. Fassmer SY – Nb. No.: 98/1/5300

INTERING Stabilizers



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6. Dimensioning Questionnaire



Dimensioning Questionnaire

Stabilizer Anti-Heeling System Stability Test System ISTS

Parametric Roll Preventer IPRP

Project No. _____

Yard / Owner: _____ Project-/N.B.-No.: _____

Type of Vessel: _____ TEU / tdw: _____

Class: _____ Delivery: _____ Mains Supply: _____ V, _____ Hz

Lbp: _____ m B: _____ m BWL: _____ m Draught: _____ m

Double bottom: _____ m (BL) Side tank-beam: _____ m GA-sketch

Tween deck: _____ m (BL) Side tank-length: _____ m Midship section

Tween deck: _____ m (BL) Frame spacing: _____ m Hull form

Freeboard deck: _____ m (BL) Web frame spacing: _____ m Drawing of possible heel/
stab tanks

Data for Stabilizer / IPRP Layout: Data for Stability Test System Layout:

1. Loading conditions for ship in service:

No.	Load condition	Displacement (t)	GMsolid (m)1)	GMfluid min. (m)2)	Remarks

1) GM_{solid} values without correction for any free surfaces.

Permissible minimum GM_{fluid} value after correction for all free surfaces incl. stabilizer tank acc. to applicable stability criteria.

Data for Anti-Heeling System Layout:

2. Cranes Shore Deck

Number : _____

Safe working load : _____ t SWL

Outreach beyond ship's side : _____ m

Slewing speed with full load : _____ rpm

5. Cargo Units

Trailer Cassette+Truck

Container Waggon

Unit weight : _____ t

Speed : _____ km/h

3. Cell Guides yes no

6. Simultaneous operation yes no

4. Ramps yes no

7. Max. asymmetric load distribution to be compensated : _____ tm

Stern ramp dimensions(LxB) : _____ x _____ m

Max. load : _____ t

Side ramp length : _____ m

Max. load : _____ t

8. Max. permissible heeling angle: _____ °

9. Required rate of anti-heeling moment : _____ tm/min

10. Ice heeling required: yes no

11. Further data & requirements (levers, distances, speeds etc.):

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